

determining a position of the head, wherein the position of the head aligns the first tubular with the second tubular;

memorizing the position of the head; and

positioning the first tubular at the memorized position.

20. (New) The method of claim 19, wherein a third tubular is positioned by recalling the memorized position.

21. (New) The method of claim 19, wherein one or more sensing devices are used to determine the position of the head.

22. (New) The method of claim 21, wherein each of the one or more sensing devices comprises a linear transducer.

23. (New) The method of claim 19, wherein a telescopic arm is used to position the head.

24. (New) The method of claim 23, wherein a piston and cylinder assembly is used to extend or retract the telescopic arm.

25. (New) The method of claim 24, wherein a sensing device is used to determine the amount of extension or retraction of the piston and cylinder assembly.

26. (New) The method of claim 19, wherein the position of the head is memorized electronically.

27. (New) The method of claim 19, wherein the position of the head is memorized mechanically.

28. (New) The method of claim 19, wherein the position of the head is memorized optically.

29. (New) A method for aligning a first tubular with a second tubular,

comprising:

securing the first tubular in a gripping member;
aligning the second tubular with the first tubular using a remotely actuatable apparatus;
memorizing the position of the remotely actuatable apparatus when the second tubular is aligned with the first tubular;
connecting the second tubular to the first tubular; and
releasing the first tubular from the gripping member.

30. (New) The method of claim 29, further comprising:

lowering the first tubular and the second tubular;
securing the second tubular in the gripping member;
gripping a third tubular to be connected to the second tubular using the remotely controllable apparatus;
moving the remotely actuatable apparatus to position the third tubular at the memorized position; and
connecting the third tubular to the second tubular.

31. (New) The method of claim 30, further comprising adjusting the position of the third tubular before connecting to the second tubular.